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\mathbb{Z}_7 orbifold models in *M*-theory

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Abstract

Among T^7/Γ orbifold compactifications of *M*-theory, we examine models containing the particle physics standard model in four-dimensional spacetimes, which appear as fixed subspaces of the 10-dimensional spacetimes at each end of the interval, $I^1 \simeq S^1/\mathbb{Z}_2$, spanning the 11th dimension. Using the \mathbb{Z}_7 projection to break the E_8 gauge symmetry in each of the four-planes and a limiting relation to the corresponding heterotic string compactifications, we discuss the restrictions on the possible resulting gauge field and matter spectra. In particular, some of the states are non-local: they connect two fourdimensional worlds across the 11th dimension. We illustrate our programmable calculations of the matter field spectrum, including the anomalous U(1) factor which satisfies a universal Green–Schwarz relation, discuss a Dynkin diagram technique to showcase a model with $SU(3) \times SU(2) \times U(1)^5$ gauge symmetry, and discuss generalizations to higher order orbifolds.

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1. Introduction

A strong coupling limit of type IIA string theory is dual to a theory, the low-energy limit of which exhibits a target space with a 11-dimensional Lorentz invariance [1–4]; this still rather mysterious extension of string theory is known as *M*-theory. Unlike in string theory, not enough is known about the underlying dynamics of *M*-theory, so that much of the analysis relies on this low energy limit, which includes the 11-dimensional N = 1 supergravity. In turn, 11 is the maximum number of spacetime dimensions for a consistent locally supersymmetric theory, and has been studied independently of relations to string theory. The basic five different string theories and the 11-dimensional supergravity are in fact all regarded as six different special locations (limits) in the moduli space of this unifying *M*-theory [3, 4].

Just as type IIA string theory in 10-dimensional spacetime is related to N = 1 supergravity in $\mathbb{R}^{1,9} \times S^1$, the $E_8 \times E_8$ heterotic string theory is related to supergravity in $\mathbb{R}^{1,9} \times I^1$ [5]. In this latter type of models, the 11th dimension spans the interval $I^1 \simeq S^1/\mathbb{Z}_2$, where \mathbb{Z}_2 is the

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parity reflection. The boundary of this 11-dimensional spacetime thus consists of two parallel ten-planes, located at the two orbifold singularities: the end points of the 11th dimension. Local anomaly cancellation enforces the emergence of an E_8 gauge symmetry in each of the two boundary ten-planes.

Within *M*-theory compactifications of the last seven (spatial) dimensions of the $\mathbb{R}^{1,10}$ spacetime on a T^7/Γ orbifold¹, where $T^7 = \mathbb{R}^7/\Lambda$ and $\Gamma \subset \operatorname{Aut}(\Lambda)$, we explore the cases where Γ is a finite Abelian group of rotations in the first six dimensions of T^7 , twisted by the parity reflection in the last, 11th dimension. In general, all such actions fix entire copies of $\mathbb{R}^{1,3}$ located at certain *p*-dimensional 'planes', $P_{\star} \subset T^7$, fixed by the Γ action. Each such P_{\star} is then a singularity in T^7/Γ , and defines a special (1, 3+p)-dimensional spacetime $(\mathbb{R}^{1,3} \times P_{\star}) \subset (\mathbb{R}^{1,10}/\Lambda)/\Gamma$, called 'orbifold fixed plane' in [6, 7]. There, several models were constructed using $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_2) \times (S^1/\mathbb{Z}_2)$ and $T^6/(\mathbb{Z}_2 \times \mathbb{Z}_3) \times (S^1/\mathbb{Z}_2)$ orbifolds, and the four-dimensional spacetime occurs where dim $(P_*) = 0$.

In principle, the physics in these orbifold fixed planes are beset with gravitational and gauge anomalies, carried by Weyl (chiral) fermions. Thus, cancellation of these anomalies plays a crucial role in studying *M*-theory phenomenology [8]. As there can be no Weyl fermions in odd-dimensional spacetimes, odd-dimensional orbifold fixed planes can have no such anomaly. In turn, in 4k+2 dimensions, k = 0, 1, 2, ..., there are purely gravitational anomalies due to spin-1/2 and spin-3/2 Weyl fermions. Also, in 4k+2 dimensions, gauge anomaly may arise only if the left- and right-handed fermions transform differently under the gauge group.

Finally, in four-dimensional spacetime, there can be no gravitational anomaly and the gauge anomaly is generated by Weyl fermions transforming in complex representations. A cancellation of these anomalies is necessary for the quantum theory to be well defined, and leads to restrictions on the allowed gauge group representations of the theory. Generally, the four-dimensional gauge group contains one or more U(1) factors, each of which may receive non-vanishing contributions to its anomaly. A basis change easily renders all but one of these U(1) factors anomaly-free, but the anomalies in the last U(1) factor may in general only be canceled by a four-dimensional counterpart of the Green–Schwarz mechanism [9].

The massless spectra in such orbifold models are closely related to the corresponding models found by compactifying the $E_8 \times E_8$ heterotic string theory on T^6/\mathbb{Z}_N orbifolds [10] (see figure 1). *M*-theory compactified on S^1/\mathbb{Z}_2 has two fixed ten-plane boundaries with a chiral N = 1, E_8 gauge vector supermultiplet in each of them. In the $x_{11} \rightarrow 0$ limit, this 11-dimensional spacetime limits to a 10-dimensional spacetime—the two boundary ten-plane spacetimes coalescing—together with their separate copies of the E_8 gauge bundle. Without going into the details of the limiting dynamics, the massless spectrum in this limit is clearly identifiable with that in the $E_8 \times E_8$ heterotic string theory. The massless spectra of the well-studied four-dimensional $E_8 \times E_8$ heterotic string orbifold models then ought to agree with those in the $x_{11} \rightarrow 0$ limit of the corresponding orbifold compactifications of the *M*-theory.

We will see that this limiting behavior² is usefully restrictive, although certainly not sufficient to determine the *complete* spectrum. In turn, note that anomaly cancellations alone can similarly not rule out the occurrence of arbitrary multiples of collections of massless fields within which all anomalies happen to cancel. In this sense, the analysis along the lines of the work in [6, 7] provides a *minimal* consistent matter spectrum. This is quite familiar from the study of superstring compactification, where it is known that the determination of the exact

¹ The torus-compactification $\mathbb{R}^{1,9} \times (S^1/\mathbb{Z}_2) \to \mathbb{R}^{1,3} \times T^6 \times (S^1/\mathbb{Z}_2)$ is seen to result in $\mathbb{R}^{1,3} \times T^7/\mathbb{Z}_2$, where $T^6 \times S^1 = T^7$ and the \mathbb{Z}_2 parity reflection acts only on the last, 11th coordinate.

² The massless spectra obtained via this limit are consistent with known anomaly cancellation results.



Figure 1. Relations between *M*-theory and $E_8 \times E_8$ heterotic string theory orbifold models.

Table 1. The action of the orbifold group $\mathbb{Z}_7 \times \mathbb{Z}_2$ on the seven compact coordinates. The entries in the middle column are the fractions of $2\pi i$ phases; e.g., the entries in the last row signify the action $\alpha\beta$: $(z_1, z_2, z_3, x_{11}) \rightarrow (e^{2\pi i/7} z_1, e^{4\pi i/7} z_2, e^{-6\pi i/7} z_3, -x_{11})$.

Orbifold group	Group element	z_1	<i>z</i> ₂	Z3	<i>x</i> ₁₁	Number and dimensions of 'hyperplanes'
	α	0	0	0	_	two ten-planes
$\mathbb{Z}_7 \times \mathbb{Z}_2$	β	1/7	2/7	-3/7	+	seven five-planes
	lphaeta	1/7	2/7	-3/7	—	14 four-planes

number of chargeless massless states requires a considerably detailed knowledge about the compactification than is the case with charged matter [3, 4, 11].

By the same token, and without delving into the dynamics details of the $x_{11} \rightarrow 0$ limit, we can then specify a *minimal* consistent massless matter spectrum, to be refined subsequently. Nevertheless, already in its present form, this approach provides results that are both complementary to those in the literature and phenomenologically interesting.

2. Orbifold geometry and anomalies

The compactified space has the structure of a $T^7/\Gamma \simeq (T^6/\mathbb{Z}_N) \times (S^1/\mathbb{Z}_2)$ orbifold. We take the circle, S^1 to be the x_{11} direction and the coordinates of T^6 will be specified by z_1 , z_2 and z_3 with real coordinates x_5, \ldots, x_{10} ; for example, we may identify $z_1 = x_5 + ix_6$, $z_2 = x_7 + ix_8$, $z_3 = x_9 + ix_{10}$.

2.1. Geometry

From now on, we focus on \mathbb{Z}_7 : table 1 specifies the $\Gamma = \mathbb{Z}_7 \times \mathbb{Z}_2$ quotient group action by listing the fractional multiplets of $2\pi i$ phases of the first six coordinates of T^7 and the sign of the last coordinate, x_{11} . \mathbb{Z}_2 acts on x_{11} as a parity reflection and leaves invariant two ten-planes at the orbifold singularities; these are shown horizontally in figure 2.

The action of \mathbb{Z}_7 on the compact coordinates is chosen so as to preserve N = 1 supersymmetry. It leaves invariant seven five-planes (shown vertically in figure 2), spanned by x_{11} and x_1, \ldots, x_4 , the latter of which are suppressed in figure 2. The action of $\mathbb{Z}_7 \times \mathbb{Z}_2$ leaves invariant 14 four-planes which lie at the intersection of ten-planes and five-planes and represented by dots in figure 2.

In table 1, we have omitted the other elements of the orbifold group because their fixed point sets are identical to those of either β or $\alpha\beta$. Elements β^2 , β^3 , β^4 , β^5 and β^6 are in this sense equivalent to β , and the elements $\alpha\beta^2$, $\alpha\beta^3$, $\alpha\beta^4$, $\alpha\beta^5$ and $\alpha\beta^6$ are equivalent to $\alpha\beta$. The



Figure 2. Intersecting planes in the $T^6/\mathbb{Z}_7 \times S^1/\mathbb{Z}_2$ orbifold: with x_5, \ldots, x_{10} shown unraveled in the sketch on the left-hand side, and curled up on the right-hand side.

fixed-point sets are called 'hyperplanes' following the nomenclature in the literature, but we note that such '*p*-planes' are in the final orbifold non-compact only in the first four dimensions, x_1, \ldots, x_4 (dots in figure 2), and compact in the rest: x_{11} is always restricted to the interval $I^1 = S^1/\mathbb{Z}_2$ (vertical in figure 2), and x_5, \ldots, x_{10} are subject to the twisted periodic boundary conditions of $(\mathbb{R}^6/\Lambda)/\mathbb{Z}_7$, as sketched by the ovals in figure 2.

2.2. Anomalies

On the 10-dimensional plane the chiral projection of the 11-dimensional supergravity induces gravitational anomaly. To cancel this anomaly we need to introduce the Yang–Mills type of gauge fields which further induce gauge and mixed type of anomalies. The presence of some topological terms in the 11-dimensional supergravity action induces additional anomalies known as 'inflow' anomalies. Cancellation of these gravitational, quantum and inflow anomalies require a separate complement of E_8 gauge fields in each of the two ten-plane boundary spacetimes [5].

As indicated in table 1, within the 11-dimensional bulk and the 10-dimensional boundary, the next Γ -fixed structure consists of five-planes. This situation is the key difference between our \mathbb{Z}_7 -orbifolds and the models studied earlier [6, 7, 12]. Therein, each model contained intermediate Γ -fixed structures between the 10-dimensional and the 5-dimensional one. Those intermediate structures—most notably the Γ -fixed six-planes—provided pivotal information by way of anomaly cancellation requirements [13–15]. Herein, there are no such intermediate structures and therefore no additional constraints enforced by anomaly cancellation in these intermediate Γ -fixed structures.

So, in the 'next dimension down', we have five-planes, shown as vertical lines in figure 2. One of their five dimensions is spanned by x_{11} , and their remaining four dimensions, collapsed to the dots in figure 2, lie in each of the two 10-dimensional boundary components of the original *M*-theory.

Since odd-dimensional spacetimes cannot have Weyl fermions, and it is only such fermions that can carry the anomaly, the matter content within the five-planes is anomaly-free. However, we will see in the following sections that we must nevertheless introduce some states that extend through the five-planes in order to cancel anomalies on their boundary four-planes.

3. \mathbb{Z}_7 invariant groups

On a given four-plane within the boundary ten-plane, the E_8 gauge group breaks down to some subgroup \mathcal{G}_4 . The breaking depends on the embedding of the \mathbb{Z}_7 action within the E_8 group. The fundamental irreducible representation **248** of E_8 , which has rank 8 is also its

adjoint representation. Using *Mathematica*TM programs, we construct all the positive 120 roots of E_8 from the highest root [0, 0, 0, 0, 0, 0, 1, 0] and 428 eight-component \mathbb{Z}_7 vectors with coordinates taking values from among $\{\frac{1}{7}, \frac{2}{7}, \frac{3}{7}, \frac{4}{7}, \frac{5}{7}, \frac{6}{7}\}$, and chosen so as to preserve supersymmetry. Requiring supersymmetry implies that the sum of the components of a vector must add up to an integer [12]. Once the roots and the shift vectors are known, the \mathbb{Z}_7 -invariant subgroups of E_8 is found by the following procedure.

If V denotes a \mathbb{Z}_7 shift vector acting on the root lattice \mathcal{P} of group E_8 , then the set of root vectors that survives the projection

$$e^{2\pi i (\boldsymbol{P} \cdot \boldsymbol{V})} |\boldsymbol{P}\rangle = |\boldsymbol{P}\rangle, \qquad \boldsymbol{P} \in \boldsymbol{\mathcal{P}}, \tag{3.1}$$

constitutes the root vectors of a \mathbb{Z}_7 -invariant subgroup *H* in E_8 . We denote by \mathcal{W} the set of 120 positive root vectors of E_8 .

In the *first* step, we take the dot product between a shift V and each of the roots W_i 's in W. A root that satisfies $V \cdot W_i \in \mathbb{Z}$ is said to have *survived* the shift. We denote by \mathcal{T}_V this set of surviving roots, and by k_V the number of surviving roots for a particular shift V:

$$k_V := |\mathcal{T}_V|. \tag{3.2}$$

We consider all the 428 \mathbb{Z}_7 vectors and their permutations to find out all the possible values of k_V . We extensively use *Mathematica*TM and collect the values of k_V and find that it can have one of the following values:

$$k_V \in \{14, 15, 16, 21, 22, 23, 28, 30, 36, 37, 42, 63\}.$$
 (3.3)

In the *second* step, we find all the possible subgroups $H_I \subset E_8$. We use the Dynkin diagram technique and the subgroups are listed in table A1 in appendix A. We find the number of positive roots k_H for each one of these subgroups. These numbers give us indication of the possible subgroups that equation (3.3) represents. For example, if the number of surviving roots k_V for a particular shift V is 14, these 14 roots might belong to one of the four subgroups

$$SO_8 \times SU_2^2$$
, $SU_5 \times SU_3 \times SU_2$, $SU_5 \times SU_2^4$, or $SU_4^2 \times SU_2^2$, (3.4)

as found in table A1.

The *third* step is required if the subgroup is not identified unambiguously already by the values of k_V : for each $H_I \subset E_8$, we compute *m* and *r* defined as

$$m := \text{the number of } SU(2) \text{ factors, if any, in } H_I,$$

$$r := \text{the rank of } H_I.$$
(3.5)

Table A1 in appendix A lists the values of m and r used to identify a subgroup of E_8 .

Finally, in the *fourth* step, we specify a procedure to determine the identifiers *m* and *r* from the set of surviving roots found in the first step. This is shown by the following example. Take the shift vector $V = \begin{bmatrix} 1 & 1 & 0 & 2 & 0 & 0 & 3 & 0 \end{bmatrix}$ one of the permutations of $\begin{bmatrix} 1 & 1 & 2 & 3 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}$

Take the shift vector $\boldsymbol{V} = \begin{bmatrix} \frac{1}{7}, \frac{1}{7}, 0, \frac{2}{7}, 0, 0, \frac{3}{7}, 0 \end{bmatrix}$, one of the permutations of $\begin{bmatrix} \frac{1}{7}, \frac{1}{7}, \frac{2}{7}, \frac{3}{7}, 0, 0, 0, 0, 0, 0 \end{bmatrix}$. The E_8 roots that survive the shift are

$$\mathcal{T}_V :=$$

$$\begin{cases} [0, 0, 0, 0, 1, -1, 0, 0], & [1, -1, 0, 0, 0, 0, 0, 1], & [1, -1, 1, 0, 0, 0, 0, 0, -1], \\ [-1, 1, 0, 0, -1, 1, 0, 0], & [0, 0, -1, 0, 1, 0, 0, 1], & [0, 0, 0, 0, 1, 0, 0, -1], \\ [1, -1, 0, 0, 0, 1, 0, 0], & [0, 0, 0, 0, -1, 0, 1], & [0, 0, 1, 0, 0, -1, 0, -1], \\ [0, 1, -1, 1, -1, 1, -1, 0], & [-1, 0, 1, -1, 0, 0, 1, 0], & [1, -1, 1, 0, -1, 0, 0, 0], \\ [-1, 1, -1, 0, 1, -1, 0, 1], & [-1, 1, 0, 0, 1, -1, 0, -1], & [0, 0, -1, 0, 0, 0, 0, 2] \end{cases} .$$

Let z^i , i = 1, 2, ..., 15, denote these roots. We look for possible relations³ in the form $z^i + z^j = z^k$, and find the following:

$$5z^2 + z^{14} = z^1, \qquad z^3 + z^{13} = z^1, \qquad z^3 + z^{15} = z^2,$$
 (3.7*a*)

$$z^{5} + z^{9} = z^{1}, \qquad z^{5} + z^{12} = z^{2}, \qquad z^{6} + z^{8} = z^{1},$$
 (3.7b)
 $z^{6} + z^{12} = z^{3}, \qquad z^{6} + z^{15} = z^{5}, \qquad z^{7} + z^{8} = z^{2}.$ (3.7c)

$$z + z = z^{2}, \qquad z + z^{2} = z^{2}, \qquad z + z = z^{2}, \qquad (3.7c)$$

$$z^{7} + z^{9} = z^{3}, \qquad z^{7} + z^{13} = z^{5}, \qquad z^{7} + z^{14} = z^{6} \qquad (3.7d)$$

$$z + z = z, \qquad z + z = z, \qquad z + z = z, \qquad (3.7a)$$

$$z^{9} + z^{15} - z^{8} = z^{10} + z^{11} - z^{4} = z^{12} + z^{13} - z^{8} \qquad (3.7e)$$

$$z + z = z, \quad z + z = z, \quad z + z = z, \quad (3.7e)$$

$$z^{12} + z^{14} = z^{5}, \qquad z^{14} + z^{15} = z^{15}.$$
 (3.7f)

The roots z^7 , z^{10} , z^{11} , z^{12} , z^{14} and z^{15} cannot be expressed as a sum of any other of the roots (3.6), which means that they correspond to six simple roots, whence the rank of the group must be 6.

Since all 15 roots (3.6) appear in the system (3), each root is part of a root system larger than $\{-z^i, 0, z^i\}$. Therefore, each SU(2) subgroup corresponding to any of the roots (3.6) is a subgroup of a larger subgroup of E_8 , and the roots (3.6) represent no SU(2) factor subgroup of E_8 . So, looking at the surviving roots we can define the variables *m* and *r* as

m := the number of roots which do not occur in any of the equations

of the type
$$z^i + z^j = z^k$$
 (in this example, $m = 0$),
(3.8)

r := the number of roots which do not occur on the right-hand side

of any of the equations of the type $z^i + z^j = z^k$.

Proof. The justification for the agreement between the identifications (3.5) and (3.8) is simple: note first that SU(2) is the unique Lie group to have the same number, one, of each of a Cartan root, a positive (raising) root and a negative (lowering) root. As positive roots that are not themselves sums of other positive roots are by definition *simple*, the one positive root within an SU(2) factor subgroup of E_8 clearly must be simple.

Each simple positive root has a corresponding negative and their commutator results in a Cartan generator, thus jointly generating an SU(2) group. In particular, the number of simple roots must then be equal to the rank of the considered subgroup $H \subset E_8$. So, simple positive roots that, within a \mathcal{T}_V , are neither sums of other positive roots nor occur as summands in any of the positive roots, must in fact be separate SU(2) factors within the considered subgroup $H \subset E_8$.

In turn, simple positive roots that *do* occur as summands adding up to other positive roots within \mathcal{T}_V must belong to bigger root systems, belonging to factors in *H* that contain SU(2), but are bigger. Partitioning \mathcal{T}_V into such root sub-systems decomposes *H* into individual factors. Within the finite list of subgroups of E_8 , it is then possible to identify each system of surviving roots \mathcal{T}_V with the root system of the corresponding specific subgroup of E_8 (see appendix B).

Using table A1, this unambiguously identifies the roots (3.6) as belonging to the group $SO_8 \times SU_3$. We employ this analysis in the construction of the *Mathematica*TM codes and find the subgroups of E_8 that are invariant under a \mathbb{Z}_7 shift listed in table B1.

³ A relation of the type $z^i + z^j = z^k$ corresponds to the commutator $[E_{z^i}, E_{z^j}] = E_{z^k}$. So, E_{z^i}, E_{z^j} and E_{z^k} , together with two suitable Cartan generators and $E_{-z^i}, E_{-z^j}, E_{-z^k}$ generate an SU(3) subgroup of E_8 . In particular, if $z^k = z^i + z^j$ for some z^i and z^j , then z^k is not a simple root.

4. Four-dimensional models

There are 14 possible choices for \mathcal{G}_4 and including the case when E_8 is unbroken, there are 15 possible groups for the upper world four-planes and 15 possible groups for the lower world four-planes. At this moment there is no restriction on the choice of the upper world gauge group and lower world gauge group, so in the limit $x_{11} \rightarrow 0$, when the two worlds fuse (for comparison with heterotic string compactification), we end up getting $\binom{15+1}{2} = 120$ possible groups on a four-plane. We look at one of these possibilities and investigate the four-dimensional physics. Take for example $E_8 \rightarrow SU_5 \times SU_3 \times SU_2 \times U_1$ breaking. The branching⁴ rule is [16]

$$\begin{split} E_8 &\rightarrow SU_5 \times SU_5 \rightarrow SU_5 \times SU_3 \times SU_2 \times U_1 :\\ \mathbf{248} &= (\mathbf{1}, \mathbf{24}) \oplus (\mathbf{24}, \mathbf{1}) \oplus (\mathbf{5}, \overline{\mathbf{10}}) \oplus (\mathbf{\bar{5}}, \mathbf{10}) \oplus (\mathbf{10}, \mathbf{5}) \oplus (\overline{\mathbf{10}}, \mathbf{\bar{5}}) \\ &= [(\mathbf{1}, \mathbf{1}, \mathbf{1})_{(0)} \oplus (\mathbf{1}, \mathbf{1}, \mathbf{3})_{(0)} \oplus (\mathbf{1}, \mathbf{3}, \mathbf{2})_{(-5)} \oplus (\mathbf{1}, \mathbf{\bar{3}}, \mathbf{2})_{(5)} \oplus (\mathbf{1}, \mathbf{8}, \mathbf{1})_{(0)}] \\ &\oplus (\mathbf{24}, \mathbf{1}, \mathbf{1})_{(0)} \oplus [(\mathbf{5}, \mathbf{1}, \mathbf{1})_{(-6)} \oplus (\mathbf{5}, \mathbf{3}, \mathbf{1})_{(4)} \oplus (\mathbf{5}, \mathbf{\bar{3}}, \mathbf{2})_{(-1)}] \\ &\oplus [(\mathbf{\bar{5}}, \mathbf{1}, \mathbf{1})_{(6)} \oplus (\mathbf{\bar{5}}, \mathbf{\bar{3}}, \mathbf{1})_{(-4)} \oplus (\mathbf{\bar{5}}, \mathbf{3}, \mathbf{2})_{(1)}] \\ &\oplus [(\mathbf{10}, \mathbf{1}, \mathbf{2})_{(3)} \oplus (\mathbf{10}, \mathbf{3}, \mathbf{1})_{(-2)}] \oplus [(\overline{\mathbf{10}}, \mathbf{1}, \mathbf{2})_{(-3)} \oplus (\overline{\mathbf{10}}, \mathbf{\bar{3}}, \mathbf{1})_{(2)}] \\ &\rightarrow (\mathbf{1}, \mathbf{1}, \mathbf{1})_{(0)} \oplus (\mathbf{1}, \mathbf{1}, \mathbf{3})_{(0)} \oplus (\mathbf{1}, \mathbf{3}, \mathbf{2})_{(-5)} \oplus (\mathbf{1}, \mathbf{8}, \mathbf{1})_{(0)} \oplus (\mathbf{24}, \mathbf{1}, \mathbf{1})_{(0)} \oplus (\mathbf{5}, \mathbf{1}, \mathbf{1})_{(-6)} \\ &\oplus (\mathbf{5}, \mathbf{\bar{3}}, \mathbf{2})_{(-1)} \oplus (\mathbf{5}, \mathbf{3}, \mathbf{1})_{(4)} \oplus (\mathbf{10}, \mathbf{3}, \mathbf{1})_{(-2)} \oplus (\mathbf{10}, \mathbf{1}, \mathbf{2})_{(3)}. \end{split}$$

On a four-plane only the vector multiplets and the chiral multiplets survives, so at the end of the branching we keep only the \mathcal{R} part for the representations of the form $\mathcal{R} \oplus \overline{\mathcal{R}}$. The part of the surviving representations that contribute to the anomaly is

 $(1, 3, 2)_{(-5)} \oplus (5, 1, 1)_{(-6)} \oplus (5, \overline{3}, 2)_{(-1)} \oplus (5, 3, 1)_{(4)} \oplus (10, 3, 1)_{(-2)} \oplus (10, 1, 2)_{(3)}.$ (4.2) To cancel the anomaly each of the following terms must vanish,

$$I(\mathcal{G}_I) \equiv \sum_i \sum_{\mathcal{R}_I} n(\mathcal{R}_I)_i \ q_i \ I_2(\mathcal{R}_I), \qquad I(U_1)_{\text{GAUGE}} = \sum_i \ N_i \ q_i^3, \quad (4.3)$$

where \mathcal{G}_I are each of the group factor, $n(\mathcal{R}_I)_i$ are the multiplicity of each of the representation \mathcal{R}_I in the *i*th set of fields, q_i is the charge of each set of fields, $I_2(\mathcal{R}_I)$ is the second index of the representation \mathcal{R}_I and N_i is the total number of fields in each set. Note that all these multiplets have a factor of $\frac{1}{f}$ from the index theorem, where *f* is the number of five-planes for the corresponding \mathbb{Z}_N orbifold. On a given four-plane the total anomaly turns out to be

$$I(SU_5) = \frac{1}{f} (1(-6)I_2(\mathbf{5}) + 6(-1)I_2(\mathbf{5}) + 3(4)I_2(\mathbf{5}) + 3(-2)I_2(\mathbf{10}) + 2(3)I_2(\mathbf{10}))$$

$$= \frac{1}{f} (1(-6)\cdot 1 + 6(-1)\cdot 1 + 3(4)\cdot 1 + 3(-2)\cdot 3 + 2(3)\cdot 3) = 0.$$

$$I(SU_3) = \frac{1}{f} (2(-5)I_2(\mathbf{3}) + 10(-1)I_2(\bar{\mathbf{3}}) + 5(4)I_2(\mathbf{3}) + 10(-2)I_2(\mathbf{3}))$$

$$= \frac{1}{f} (2(-5)\cdot 1 + 10(-1)\cdot 1 + 5(4)\cdot 1 + 10(-2)\cdot 1) = \frac{1}{f} (-20) \neq 0.$$

$$I(SU_2) = \frac{1}{f} (3(-5)I_2(\mathbf{2}) + 15(-1)I_2(\mathbf{2}) + 10(3)I_2(\mathbf{2}))$$

$$= \frac{1}{f} (3(-5)\cdot 1 + 15(-1)\cdot 1 + 10(3)\cdot 1) = 0.$$

(4.4)

⁴ The double-headed arrow, \rightarrow , denotes a projection to a subset.

$$I(U_1)_{\text{GAUGE}} = \frac{1}{f} (6(-5)^3 + 5(-6)^3 + 30(-1)^3 + 15(4)^3 + 30(-2)^3 + 20(3)^3) \neq 0.$$

So there are gauge and U_1 anomalies for this example. Of all the possible choices of gauge groups in table B1, only three of them do not contribute to any anomaly. They are $E_7 \times U_1$, $SO_{12} \times U_1^2$ and $SO_{10} \times SU_2 \times U_1^2$. The branching rules for these three groups are the following.

$$\begin{aligned} (1) \ E_8 \to E_7 \times SU_2 \to E_7 \times U_1: \\ & 248 = (1,3) \oplus (133,1) \oplus (56,2) \\ & = [1_{(-1)} \oplus 1_{(0)} \oplus 1_{(1)}] \oplus 133_{(0)} \oplus [56_{(-\frac{1}{2})} \oplus 56_{(\frac{1}{2})}]. \end{aligned}$$
(4.5)

$$(2) \ E_8 \to SO_{16} \to SO_{12} \times SU_2 \times SU_2 \to SO_{12} \times U_1^2: \\ 248 = 120 \oplus 128 \\ & = [(66,1,1) \oplus (12,2,2) \oplus (1,1,3) \oplus (1,3,1)] \oplus [(32,2,1) \oplus (32,1,2)] \\ & = [(66,1)_{(0)} \oplus [(12,2)_{(-\frac{1}{2})} \oplus (12,2)_{(\frac{1}{2})}] \oplus [(1,1)_{(-1)} \oplus (1,1)_{(0)} \oplus (1,1)_{(1)}] \\ & \oplus (1,3)_{(0)}] \oplus [(32,2)_{(0)} \oplus [(32,1)_{(-\frac{1}{2})} \oplus (32,1)_{(\frac{1}{2})}]] \\ & = [66_{(0)(0)} \oplus [[12_{(-\frac{1}{2})(-\frac{1}{2})} \oplus 12_{(\frac{1}{2})(-\frac{1}{2})}] \oplus [12_{(-\frac{1}{2})(\frac{1}{2})} \oplus 12_{(\frac{1}{2})(\frac{1}{2})}]] \\ & \oplus [1_{(0)(-1)} \oplus 1_{(0)(0)} \oplus 1_{(0)(1)}] \oplus [1_{(-1)(0)} \oplus 1_{(0)(0)} \oplus 1_{(1)(0)}]] \\ & \oplus [[32_{(-\frac{1}{2})(0)} \oplus 32_{(\frac{1}{2})(0)}] \oplus [32_{(0)(-\frac{1}{2})} \oplus 32_{(0)(\frac{1}{2})}]]. \end{aligned}$$
(4.6)

$$(3) \ E_8 \to SO_{16} \to SO_{10} \times SU_4 \to SO_{10} \times SU_2^2 \times U_1 \to SO_{10} \times SU_2 \times U_1^2: \\ 248 = 120 \oplus 128 \\ & = [(45,1) \oplus (10,6) \oplus (1,15)] \oplus [(16,4) \oplus (16,\frac{1}{4})] \\ & = [(45,1,1)_{(0)} \oplus (10,1,1)_{(2)} \oplus (10,1,1)_{(-2)} \oplus (10,2,2)_{(0)}] \\ & \oplus [(11,1,1)_{(0)} \oplus (1,3,1)_{(0)} \oplus (1,1,3)_{(0)} \oplus (1,2,2)_{(2)} \oplus (1,2,2)_{(-2)}]] \\ & \oplus [(16,2,1)_{(1)} \oplus (16,1,2)_{(-1)}] \oplus [(16,2,1)_{(-1)} \oplus (16,1,2)_{(1)}]] \\ & = [(45,1)_{(0)(0)} \oplus [(10,1)_{(0)(2)} \oplus (10,1)_{(0)(-2)} \oplus [(10,2)_{(-\frac{1}{2})(0)} \oplus (10,2)_{(\frac{1}{2})(0)}]] \\ & \oplus [(1,1,0)_{(0)} \oplus (1,3)_{(0)(0)} \oplus [(1,1)_{(-1)(0)} \oplus (1,1)_{(0)(0)} \oplus (1,1)_{(10)(0)} \oplus (1,1)_{(0)(0)} \oplus (1,1)_{(-\frac{1}{2})(-1)} \oplus (16,1)_{(\frac{1}{2})(-1)}]] \\ & \oplus [(16,2)_{(0)(1)} \oplus [(16,1)_{(-\frac{1}{2})(-1)} \oplus (16,1)_{(\frac{1}{2})(-1)}]] \\ & \oplus [(16,2)_{(0)(-1)} \oplus [(16,1)_{(-\frac{1}{2})(1)} \oplus (16,1)_{(\frac{1}{2})(-1)}]] \\ & \oplus [(16,2)_{(0)(-1)} \oplus [(16,$$

However, the final massless contents of these choices are non-chiral. So, we look for a possible solution to this problem. So far, we do not have any mechanism to cancel anomaly on a given four-dimensional plane, which requires twisted states and possibly some contribution from the five-planes. We now turn into these.

5. M-theory models from string theory orbifolds

We explained in the introduction how four-dimensional orbifold models constructed from $E_8 \times E_8$ heterotic string theory are related to those constructed in *M*-theory. In this section we would like to emphasize the relationship a little further. In order to do that, we need to consider the possible four-dimensional string compactifications on 'our' orbifolds. In [10, 17], Katsuki *et al* have listed all the possible gauge groups on a four-dimensional plane for \mathbb{Z}_N orbifolds in general. For the \mathbb{Z}_7 orbifold there are 39 such models. They have also listed

massless twisted and untwisted states for all the \mathbb{Z}_N orbifold models, except for \mathbb{Z}_8 and \mathbb{Z}_{12} because there are too many massless states in those cases, and this number increases as one goes to higher order orbifolds. However the U(1) charges of the matter representations were omitted. These U(1) charges are necessary if one wants to relate the model with one in the M-theory construction. We follow [18, 19] to calculate these charges.

5.1. Anomalous U(1) gauge symmetry

All the models listed in [10, 17] have at least one U(1) factor. As we will show, in any of these models we can choose the U(1) basis in such a way that at most one U(1) factor is anomalous. The presence of U(1) anomalies is allowed in this kind of orbifold theories as they can be canceled by a four-dimensional version of the universal Green–Schwarz mechanism [9].

Let us take the anomalous gauge group, $\prod_a G_a \times U(1)_A$. The charge Q_A associated with the anomalous U(1) factor is related to a constant δ_{GS} by Tr $Q_A = 96\pi^2 \sqrt{k_A} \delta_{GS}$. Here k_A is the level of $U(1)_A$ and the constant δ_{GS} has a unique value. For models with only one U(1)factor the following universality relation is satisfied,

$$\frac{1}{k_a} \prod_{G_a} T(R) Q_A = \frac{1}{3} \operatorname{Tr} Q_A^3 = \frac{1}{24} \operatorname{Tr} Q_A \equiv 8\pi^2 \delta_{\mathrm{GS}},$$
(5.1)

where 2T(R) is the index of the representation R and the charge Q_A has been rescaled so that $k_A = 1$. This is referred to as the universal GS relation. By forming suitable linear combinations of more than 1 U(1) factor, it is always possible to change the basis so that at most 1 U(1) factor is anomalous. The universal relation in that case is

$$\frac{1}{k_a} \operatorname{Tr}_{G_a} T(R) Q_A = \operatorname{Tr} Q_B^2 Q_A = \frac{1}{3} \operatorname{Tr} Q_A^3 = \frac{1}{24} \operatorname{Tr} Q_A = 8\pi^2 \delta_{\mathrm{GS}}, \quad (5.2)$$

where Q_B is the charge with respect to any of the non-anomalous U(1) factors.

To illustrate the above procedure we give an example: consider the model, $E_8 \times E'_8 \rightarrow SU(8) \times U(1)_A \times E_6 \times SU(2) \times U(1)_B$. We use *Mathematica*TM to find out the untwisted and twisted states along with their charges.

Untwisted states

(i) We find out the 248 roots of E_8 from the following.

$$P' = [\pm 1, \pm 1, 0, 0, 0, 0, 0, 0] \equiv [\pm 1, \pm 1, 0^{6}],$$
(5.3)

$$P^{I} = \left[\pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}, \pm\frac{1}{2}\right],\tag{5.4}$$

where underline indicates the inclusion of all permutations, and one must select an even number of minus signs in (5.4). We also include the eight Cartan roots, [0, 0, 0, 0, 0, 0, 0, 0, 0].

- (ii) Multiply these roots P^I with the shift V^I . For the example at hand, $V^I = \frac{1}{7}[1, 1, 1, 1, 1, 1, 1, -1]$ for the group $SU(8) \times U(1)_A$. Look for roots that give $P^I \cdot V^I \in \mathbb{Z}$. This gives us the untwisted states.
- (iii) Look for a suitable U(1) basis. The general procedure is described below⁵.

A suitable U(1) basis

The E_8 Kac–Moody algebra consists of the ∂X^I and $e^{iP^IX^I}$ operators, where P^I are nonzero roots of E_8 and ∂X^I corresponds to the Cartan parts. Now, the shift vector V^I breaks the E_8 group to a gauge group, whose Kac–Moody algebra consists of ∂X^I and $e^{iP^IX^I}$, where

⁵ Thanks to Tatsuo Kobayashi for explaining this.

 P^{I} are the surviving roots satisfying $P^{I} \cdot V^{I} \in \mathbb{Z}$. Suppose that the unbroken gauge group is $G_{7} \times U(1)$, for some simple rank-7 subgroup $G_{7} \subset E_{8}$. This U(1) corresponds to a linear combination of ∂X^{I} , i.e., $\sum_{I} a_{I} \partial X^{I}$. These coefficients are fixed so that $\sum_{I} a_{I} \partial X^{I}$ commutes with the non-Abelian part, G_{7} , implying that

$$\sum_{I} a_I P^I = 0. \tag{5.5}$$

The procedure to fix a U(1) basis is essentially the same even when the unbroken gauge group includes two or more U(1) factors. For an example, let us consider the case where the unbroken gauge group is $G_6 \times U(1)^2$. The two U(1) factors correspond to linear combinations of ∂X^I , i.e., $\sum_I a_I^{(1)} \partial X^I$ and $\sum_I a_I^{(2)} \partial X^I$. They should satisfy

$$\sum_{I} a_{I}^{(1)} P^{I} = 0, \qquad \sum_{I} a_{I}^{(2)} P^{I} = 0, \tag{5.6}$$

for P^I satisfying $P^I \cdot V^I \in \mathbb{Z}$, and they should be orthogonal to each other, i.e.,

$$\sum_{I} a_{I}^{(1)} a_{I}^{(2)} = 0.$$
(5.7)

In the $(a^{(1)}, a^{(2)})$ -plane, there exists one degree of freedom to rotate the basis. If both U(1) factors are anomaly-free, we can choose any basis. If one of the U(1) factors is anomalous, we identify it. Finally, if both U(1) factors are anomalous, we rotate to a basis wherein one U(1) is anomaly-free, leaving the other to be anomalous.

In this way, we find that the U(1) basis for the shift $V^{I} = \frac{1}{7}[1, 1, 1, 1, 1, 1, 1, 1, -1]$ is given by $7V^{I}$. Once the basis vector is fixed, the product of the basis vector with the surviving P^{I} gives the untwisted states and their charges as

$$(\mathbf{56})_{-1} \oplus (\overline{\mathbf{28}})_{-2} \oplus (\overline{\mathbf{8}})_3. \tag{5.8}$$

We do the same for the other E'_8 factor, where the shift is $V^I = \frac{1}{7}[1, 1, 1, 1, 1, 1, 0, 0]$, the U(1) charge basis is again $7V^I$, and the gauge group is now $E_6 \times SU(2) \times U(1)_B$. We obtain the untwisted states:

$$(27, 2)_1 \oplus (27, 1)_2 \oplus (1, 2)_{-3}.$$
 (5.9)

Together, the $SU(8) \times U(1)_A \times E_6 \times SU(2) \times U(1)_B$ representation of the untwisted states is (56, 1, 1)_{-1,0} \oplus ($\overline{28}$, 1, 1)_{-2,0} \oplus ($\overline{8}$, 1, 1)_{3,0} \oplus (1, 27, 2)_{0,1} \oplus (1, $\overline{27}$, 1)_{0,2} \oplus (1, 1, 2)_{0,-3}. (5.10)

Twisted states

- (i) Find the 248 roots of E_8 from equations (5.3) and (5.4).
- (ii) Multiply the shift V^I with k, the twisted sector index. If any of the components of $k V^I$ is outside [-3/7, 3/7], we simplify as follows: take for example $V^I = \frac{1}{7}[3, 3, 2, 2, 2, 2, 1, -1]$ and k = 4, which gives $k V^I = \frac{1}{7}[12, 12, 8, 8, 8, 8, 4, -4]$. Now we simplify $k V^I$ by reducing each component of $7(k V^I)$ modulo 7, producing $k V^I \cong \frac{1}{7}[-2, -2, 1, 1, 1, 1, -3, 3] = : w$.
- (iii) Calculate the shifted momenta $\tilde{P}^I = P^I + w$.
- (iv) Do the same for the other E_8' factor. Call this $\widetilde{P}^{I'}$.
- (v) Compute the momenta $\tilde{P}^{\hat{l}} = (\tilde{P}^{I}, \tilde{P}^{I'})$ and then $\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^{2}$. This gives a total of 248 × 248 values.

¹⁰

(vi) Calculate $\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^2$ from the mass formula for the left moving twisted sectors (in the light-cone gauge),

$$\frac{1}{8}m_L^2 = \frac{1}{2}\sum_{i=1}^3 \left(p_L^i\right)^2 \delta_{k,0} + \frac{1}{2}\sum_{\hat{I}=1}^{16} (\tilde{P}^{\hat{I}})^2 + N_L^{(k)} - 1 + c^{(k)}.$$
(5.11)

The term $N_L^{(k)}$ is the oscillator number and takes the fractional value which is multiple of $\frac{1}{N}$, where *N* is the order of the orbifold group. For \mathbb{Z}_7 orbifold the zero-point energy is the same for any twisted sector and is equal to $c^{(k)} = 2/7$. The untwisted states correspond to k = 0 and the momenta p_L^i are associated with the compact coordinates X_L^j , where $j = 3, \ldots, 8$. For twisted states the term $\sum (p_L^i)^2$ does not contribute to the mass equation. Since the value of $N_L^{(k)}$ is a multiple of $\frac{1}{N}$, we obtain $N_L^{(k)} = 0, \frac{1}{7}, \ldots, \frac{6}{7}$. So, from (5.11) we obtain

$$\sum_{\hat{I}=1}^{16} (\tilde{P}^{\hat{I}})^2 = -2N_L^{(k)} + \frac{10}{7}.$$
(5.12)

For the various possible values of $N_L^{(k)}$,

$$\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^2 = \frac{10}{7}, \frac{8}{7}, \frac{6}{7}, \frac{4}{7}, \frac{2}{7}, 0, -\frac{2}{7}.$$
(5.13)

Since $\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^2$ is positive, the maximum and minimum values of $\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^2$ are $\frac{10}{7}$ and 0, respectively. This gives $\sum_{\hat{l}=1}^{16} (\tilde{P}^{\hat{l}})^2 = \frac{10}{7}, \frac{8}{7}, \frac{6}{7}, \frac{4}{7}, \frac{2}{7}$ for $7N_L^{(k)} = 0, 1, 2, 3, 4$, respectively.

- (vii) Now look for $\tilde{P}^{\hat{I}}$ in step (v), which gives $\sum_{\hat{I}=1}^{16} (\tilde{P}^{\hat{I}})^2 = \frac{10}{7}, \frac{8}{7}, \frac{6}{7}, \frac{4}{7}$ or $\frac{2}{7}$.
- (viii) Take the same U(1) basis as in the untwisted case and multiply it with the surviving $\tilde{P}^{\hat{I}}$. This produces the twisted states and their charges in the k = 1, 2 and 4 sectors as follows:

$$k = 1: \quad 7(\bar{\mathbf{8}}; \mathbf{1}, \mathbf{1})_{-\frac{13}{7}, \frac{6}{7}} \oplus 7(\mathbf{1}; \mathbf{1}, \mathbf{2})_{\frac{8}{7}, -\frac{15}{7}} \oplus 35(\mathbf{1}; \mathbf{1}, \mathbf{1})_{\frac{8}{7}, \frac{6}{7}},$$

$$k = 2: \quad 7(\bar{\mathbf{8}}; \mathbf{1}, \mathbf{1})_{-\frac{5}{7}, \frac{12}{7}} \oplus 7(\mathbf{1}; \mathbf{1}, \mathbf{2})_{\frac{16}{7}, -\frac{9}{7}} \oplus 7(\mathbf{1}; \mathbf{1}, \mathbf{1})_{\frac{16}{7}, \frac{12}{7}},$$

$$k = 4: \quad 7(\mathbf{8}; \mathbf{1}, \mathbf{2})_{-\frac{3}{7}, \frac{3}{7}}.$$

(5.14)

Anomaly

For the group $SU(8) \times U(1)_A \times E_6 \times SU(2) \times U(1)_B$ the shift may be written as $V^{\hat{l}} = (1^7, -1)(1^6, 0^2)/7$. We have two charge basis vectors: $V^{\hat{l}}_A = (1^7, -1)(0^8)$ and $V^{\hat{l}}_B = (0^8)(1^6, 0^2)$. From the charge basis vectors, we calculate the level of U(1) as

$$k_{\mathcal{Q}} = 2 \sum_{\hat{l}=1}^{16} (V_{\mathcal{Q}}^{\hat{l}})^2.$$
(5.15)

This gives $k_A = 16$ and $k_B = 12$. Note that there is no E_6 representation in the twisted sector, which tells us that $U(1)_B$ is anomalous. Using the representation index in [20, 16] we

calculate the Tr_{*G_a} T(R) Q_B, Tr Q_B, Tr Q_B^3 and Tr Q_A^2 Q_B as</sub>*

$$\begin{aligned} & \underset{SU_8}{\text{Tr}} T(R) \mathcal{Q}_B = 7 \times \frac{1}{2} \times \frac{6}{7} + 7 \times \frac{1}{2} \times \frac{12}{7} + 14 \times \frac{1}{2} \times \frac{3}{7} = 12, \\ & \underset{E_6}{\text{Tr}} T(R) \mathcal{Q}_B = 2 \times \frac{6}{2} \times 1 + 1 \times \frac{6}{2} \times 2 = 12, \\ & \underset{SU_2}{\text{Tr}} T(R) \mathcal{Q}_B = 27 \times \frac{1}{2} \times 1 + 1 \times \frac{1}{2} \times (-3) + 7 \times \frac{1}{2} \times \left(\frac{-15}{7}\right) \\ & \quad + 7 \times \frac{1}{2} \times \left(\frac{-9}{7}\right) + 56 \times \frac{1}{2} \times \frac{3}{7} = 12, \end{aligned}$$
(5.16)

$$& \underset{Tr}{\text{Tr}} \mathcal{Q}_B^3 = 54 + 54 - 6 + 186 = 288, \\ & \underset{Tr}{\text{Tr}} \mathcal{Q}_B^3 = 54 + 216 - 54 + 216 = 432, \\ & \underset{Tr}{\text{Tr}} \mathcal{Q}_A^2 \mathcal{Q}_B = 192. \end{aligned}$$

With these values, all the traces are related as

$$\operatorname{Tr}_{G_a} T(R) Q_B = \frac{1}{16} \operatorname{Tr} Q_A^2 Q_B = \frac{1}{36} \operatorname{Tr} Q_B^3 = \frac{1}{24} \operatorname{Tr} Q_B = 12.$$
(5.17)

We rescale the charge as $Q_A \rightarrow \sqrt{k_A} Q_A$ and $Q_B \rightarrow \sqrt{k_B} Q_B$ which gives the universal GS relation

$$\operatorname{Tr}_{G_a} T(R) Q_B = \operatorname{Tr} Q_A^2 Q_B = \frac{1}{3} \operatorname{Tr} Q_B^3 = \frac{1}{24} \operatorname{Tr} Q_B = 12.$$
(5.18)

In this way it is possible to find all the charges of the twisted and untwisted matter content in [10] and to calculate the universal GS relation, ensuring all models to be consistent and anomaly free.

5.2. Four-dimensional M-theory models

In section 4, we found $\binom{15+1}{2}$ *M*-theory models. But all of them were either anomalous or free of chiral fermions. In analogy with the string theory models, now we conclude that there are 39 four-dimensional *M*-theory models which are free of anomalies. Gratifyingly, they turn out to be the same models as are listed in [10, 17]. If one of the gauge groups in table 6 of [10] represents the symmetry group of the upper four-plane (figure 2) then the other one represents the group on the lower four-plane. In the limit $x_{11} \rightarrow 0$, the matter spectrum for a model is given by the untwisted and twisted states in table 6 and table 23 of [10].

In the $SU(8) \times U(1)_A \times E_6 \times SU(2) \times U(1)_B$ example given in the previous section, the untwisted states are represented by equation (5.10) and the twisted states are represented by equation (5.14). This is an interesting model, in the k = 4 twisted sector the states are charged with respect to the gauge groups of both the lower and the upper four-dimensional world, i.e., both SU_8 and $E_6 \times SU_2$, respectively.

Such states, which carry charges in both four-dimensional worlds, *must* be represented by an extended object, which stretches from one world to the other. In this case, it means that the seven (8, 1, 2)-states must be representable by an extended object (a suitable *p*-brane) stretching along the x_{11} coordinate, with one 'end' constrained to one world, the other to the other world. By the same argument, *any* state which must carry nonzero gauge charges with respect to the gauge groups in both the 'lower' and the 'upper' world, must be represented by an extended object, stretched along x_{11} from one world to the other. In effect, such models include modes of interaction between two otherwise isolated four-dimensional worlds, separated by the x_{11} coordinate.



Figure 3. Extended Dynkin diagram of E_8 . The numbers in the circles are the Kac labels. The extended root is α^0 .

From table 23 of [10], we find that there are 10 models where this phenomenon occurs. In our *M*-theory models, it is the five-planes that connect the two four-plane worlds, so these twisted states must 'live' in the five-planes. This is the contribution from the five-planes that we expected in section 2.2.

6. Four-dimensional gauge groups with one Wilson line

If we denote the lattice of the six-dimensional torus by Λ , then for the \mathbb{Z}_7 orbifold Λ must be the SU_7 lattice, which in turn implies that we can add only one Wilson line. For \mathbb{Z}_8 and \mathbb{Z}_{12} the number of Wilson lines depends on the number of lattice choices for Λ , which can be found in [21]. These Wilson lines provide extra shifts and break the four-dimensional gauge groups to smaller and more realistic groups such as $SU_3 \times SU_2 \times U_1^5$.

In section 3 we have shown how to find a subgroup of E_8 that survives a \mathbb{Z}_7 shift vector V. There is an alternate way of identifying the surviving gauge group [22]. This is known as the Dynkin diagram technique, originally proposed by Kac and Peterson [23]. In this technique, one takes the extended Dynkin diagram E_8 and looks for a redefined shift vector, which satisfies the same condition as before, $P \cdot V \in \mathbb{Z}$. This results in removing some circles from the Dynkin diagram which gives the surviving subgroup. Herein, we follow the work of [22].

The extended Dynkin diagram of E_8 is shown in figure 3. The highest root θ of E_8 is given by

$$\theta = \sum_{i=1}^{\prime} n_i \alpha^i = 2\alpha^1 + 3\alpha^2 + 4\alpha^3 + 5\alpha^4 + 6\alpha^5 + 4\alpha^6 + 2\alpha^7 + 3\alpha^8, \tag{6.1}$$

where α^i , i = 1, ..., 8, are the simple roots of E_8 , r is the rank and the coefficients n_i are the Kac labels. In the diagram, α^0 is the negative of the highest root, $\alpha^0 = -\theta$.

We expand the \mathbb{Z}_7 shift vector in the Dynkin basis $\{\gamma_i\}$, satisfying $\gamma_i \cdot \alpha^j = \delta_i^j$,

$$V = \frac{1}{N} \sum_{i=1}^{r} s_i \gamma_i, \tag{6.2}$$

where N is the order of the shift vector and $s_i = N \alpha^i \cdot V$. We define s_0 as

$$s_0 \equiv N(1 - \theta \cdot V) = N - \sum_{i=1}^8 n_i s_i,$$
 (6.3)

and define a Kac label for the simple root α^0 as $n_0 = 1$. We look for a set of integers s_I , where I = 0, ..., 8, that satisfy

$$\sum_{I=0}^{8} n_I s_I = N, \qquad s_I \ge 0. \tag{6.4}$$

For each nonzero value in the set s_I , we remove the *I*th circle from the extended Dynkin diagram and read off the surviving group from the remaining circles in the diagram. Let

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Figure 4. The extended Dynkin diagram of E_8 with three dots removed is shown on the left. The extended Dynkin diagrams of SU_2 and SO_{10} are shown on the right.

 $G = G_1 \times G_2 \times \cdots$ be the unbroken subgroup obtained in this way, where each G_x factor is a simple group.

Our next step is to add a Wilson line which can be realized by a shift vector 'a'. We expand 'a' in terms of the E_8 's fundamental weights as

$$a = \frac{1}{N} \sum_{i=1}^{8} w_i \gamma_i,$$
(6.5)

where the set of integers $w_i \ge 0$ satisfies a similar condition as s_I in equation (6.4). We define the highest root $\theta^{G_x} = -\alpha^{G_x}$ of the simple group G_x as

$$\theta^{G_x} = \sum_{i \in J_x} n_i^{G_x} \alpha^i, \tag{6.6}$$

where J_x is the set of indices *i* for each α^i that constitutes the group G_x , which includes the root α^0 if it belongs to G_x . The coefficients $n_i^{G_x}$ are the Kac labels for G_x . For each G_x we find out the extended Dynkin diagram by adding the root α^{G_x} with the Kac label $n_0^{G_x} = 1$. This is similar to adding α^0 in the previous step. For the simple group G_x that contains the root α^0 , we define $w_0 \ge 0$ as

$$w_0 \equiv N\alpha^0 \cdot a = -\sum_{i=1}^8 n_i w_i,$$
 (6.7)

where n_i are the Kac labels of E_8 , $n_i = \{2, 3, 4, 5, 6, 4, 2, 3\}$. We also define the coefficients $w_0^{G_x}$ as

$$\sum_{i \in J_x} n_i^{G_x} w_i + w_0^{G_x} = N.$$
(6.8)

Our problem now reduces to finding the right set of integers that satisfy equation (6.8) and

$$\sum_{I=0}^{5} n_I w_I = 0 \pmod{N},$$
(6.9)

where $n_I = \{n_0, n_i\} = \{1, n_i\}.$

We illustrate this process by giving an example⁶. We take a group from table B1, say, $SO_{10} \times SU_2 \times U_1^2$ and look for its possible breaking with a Wilson line. One of the choices for the coefficients s^I that satisfies equation (6.4) and breaks E_8 to $SO_{10} \times SU_2 \times U_1^2$ is $[s_0|s_i] = [0|11000010]$. We can safely remove the roots α^1 , α^2 and α^7 from the extended Dynkin diagram of E_8 , the resulting diagram is shown in figure 4. We add the roots $\alpha^{SO_{10}}$ and α^{SU_2} and get the extended Dynkin diagram for SO_{10} and SU_2 , respectively.

⁶ In fact, we may use the Dynkin diagram technique to verify the list of all \mathbb{Z}_7 -invariant subgroups of E_8 as listed in table B1, which we have found by the alternate, computational method described above.

$[\omega_i \omega_0\omega_0^{SU_2}\omega_0^{SO_{10}}]$	Group	$[\omega_i \omega_0 \omega_0^{SU_2} \omega_0^{SO_{10}}]$	Group
[00000000 077]	$SO_{10} \times SU_2$	Not possible	$SU_3 \times SU_2^3$
Not possible	SO_{10}	[00001000 165]	$SU_3 \times SU_2^2$
Not possible	$SO_8 \times SU_2$	[00010100 524]	$SU_3 \times SU_2$
[00200000 615]	SO_8	[00110100 163]	SU_3
[00600100 070]	$SU_5 \times SU_2$	Not Possible	SU_2^5
[00000100 346]	SU_5	[00201000 073]	$SU_2^{\overline{4}}$
Not possible	$SU_4 \times SU_2^3$	[00101000 434]	$SU_2^{\overline{3}}$
[00003001 070]	$SU_4 \times SU_2^2$	[00111000 612]	SU_2^2
[00010000]255]	$SU_4 \times SU_2^2$	[00111100]251]	SU_2
[00110000]524]	SU_4	Not possible	U_{1}^{8}

Table 2. Table for the breaking of $SO_{10} \times SU_2 \times U_1^2$ with one Wilson line; the U_1 factors are suppressed.

The highest root of SO_{10} is (0, 1, 0, 0, 0) which is written as

$$\theta^{SO_{10}} = 1\alpha^3 + 2\alpha^4 + 2\alpha^5 + 1\alpha^8 + 1\alpha^6, \tag{6.10}$$

where $\alpha^3 = (2, -1, 0, 0, 0)$, $\alpha^4 = (-1, 2, -1, 0, 0)$, $\alpha^5 = (0, -1, 2, -1, -1)$, $\alpha^8 = (0, 0, -1, 2, 0)$ and $\alpha^6 = (0, 0, -1, 0, 2)$ are the simple roots of SO_{10} . The Kac labels are found from the metric tensors in table 7 of [16]. This gives $n_i^{SO_{10}} = \{1, 2, 2, 1, 1\}$. For SU_2 group $n_i^{SU_2} = \{1\}$. We look for coefficients in the form $[\omega_i | \omega_0 \omega_0^{SU_2} \omega_0^{SO_{10}}]$ that satisfy the following conditions

$$w_0 + 2w_1 + 3w_2 + 4w_3 + 5w_4 + 6w_5 + 4w_6 + 2w_7 + 3w_8 = 0 \pmod{7},$$

$$w_0^{SO_{10}} + w_3 + 2w_4 + 2w_5 + w_6 + w_8 = 7,$$

$$w_0^{SU_2} + w_0 = 7.$$
(6.11)

We use *Mathematica*TM and find the possible breaking pattern of $SO_{10} \times SU_2 \times U_1^2$, shown in table 2. In the table, 'Not possible' means that we could not find a solution to the equation (6.11) that would result in the corresponding group which is a subgroup of $SO_{10} \times SU_2 \times U_1^2$. It is possible to get grand-unifying groups, such as $SO_{10} \times U_1^3$ or $SU_5 \times U_1^4$, and a standard model type gauge group, $SU_3 \times SU_2 \times U_1^5$, with an additional shift in the E_8 lattice. However, there are redundancies in the final massless contents. Take for example the $E_8 \to SO_{10} \times SU_2 \times U_1^2 \to SU_3 \times SU_2 \times U_1^5$ branching, with the U_1 charges omitted:

$$248 \to 1(8,1) \oplus 1(1,3) \oplus 20(1,2) \oplus 15(3,1) \oplus 15(\overline{3},1) \oplus 6(3,2) \oplus 6(\overline{3},2) \oplus 35(1,1).$$
(6.12)

After truncating the antichiral states, which affects only the multiplicity factors of some of the states, the massless spectrum on any one of the seven four-planes within one ten-plane (figure 2) is, somewhat formally:

$$248 \twoheadrightarrow \frac{1}{7} [1(8,1) \oplus 1(1,3) \oplus 14(1,2) \oplus 15(3,1) \oplus 8(3,1) \oplus 6(3,2) \oplus 4(3,2) \oplus 27(1,1)].$$
(6.13)

That is, equation (6.13) gives the contribution of the indicated massless states to the various index theorems within any one of the seven four-planes. In fact, as the compact space spanned by x_5, \ldots, x_{10} is unobservably small, the seven four-planes in the upper ten-plane effectively coalesce into one four-dimensional world, with the particle content indicated within the square

brackets of equation (6.13); the analogous statement holds for the seven four-planes within the lower ten-plane (see figure 2).

Using the above procedure it is possible to find the symmetry breaking pattern of all the groups listed in table B1 in appendix B.

7. \mathbb{Z}_8 and \mathbb{Z}_{12} orbifold models

To continue the search for four-dimensional models by compactifying *M*-theory on higher order orbifolds, one should take a look at the $S^1/\mathbb{Z}_2 \times T^6/\mathbb{Z}_8$ and $S^1/\mathbb{Z}_2 \times T^6/\mathbb{Z}_{12}$ orbifolds. The action of the orbifold group elements on the compact coordinates is similar to that in table 2, except that β^4 in \mathbb{Z}_8 , and β^3 , β^4 elements in \mathbb{Z}_{12} , together with their α -twisted versions, have additional fixed-point sets, which need to be counted. The network of intersecting fixed-point planes now includes ten,- seven,- six,- five- and four-planes, similar to those found in [6, 7]. The \mathbb{Z}_8 and \mathbb{Z}_{12} invariant groups that survive on a ten-plane can again be found using a *Mathematica*TM program analogous to that used for the \mathbb{Z}_7 orbifold. As the first step, the list of \mathbb{Z}_8 and \mathbb{Z}_{12} shift vectors required for such computations has been constructed: there are 809 \mathbb{Z}_8 and 6309 \mathbb{Z}_{12} vectors that satisfy the supersymmetry-preserving condition. This includes order-2, -3 and -4 shifts, which respectively generate \mathbb{Z}_2 , \mathbb{Z}_3 and \mathbb{Z}_4 subgroups of either \mathbb{Z}_8 or \mathbb{Z}_{12} .

We expect the massless spectra of four-dimensional models constructed from the $S^1/\mathbb{Z}_2 \times T^6/\mathbb{Z}_N$ orbifold, in the limit $x_{11} \to 0$, to be equivalent to those obtained from $E_8 \times E_8$ string theory on T^6/\mathbb{Z}_N orbifolds [24]. In [10] all the \mathbb{Z}_N invariant subgroups have been listed along with the untwisted states for each of these groups. The untwisted states are obtained in a way similar to the \mathbb{Z}_7 orbifold as explained in section 5.1. For the twisted states we have an additional restriction, which are selected by a GSO projection operator [19]. Since the number of twisted states is too large, [10] lists only the untwisted states; the U(1) charges are also omitted for brevity but are computed as done above.

For \mathbb{Z}_N orbifolds in string theory the shift vectors are chosen to preserve both the supersymmetry and modular invariance restrictions. In *M*-theory, however, a precise analog of the latter restriction is lacking. It therefore does not follow that the orbifold models listed in [10] would turn out to be the same as those models constructed by the present method. This problem is still open and needs to be explored. Considering the fact that \mathbb{Z}_7 orbifold models from *M*-theory and string theory turn out to be the same, one would expect this also for \mathbb{Z}_8 and \mathbb{Z}_{12} orbifold models.

8. Conclusion

We have examined the synergistic application of several related techniques used to determine the massless spectrum of $T^6/\mathbb{Z}_7 \times S^1/\mathbb{Z}_2$ orbifolds in *M*-theory. This gives us two pairs of four-plane worlds separated by a line segment. We have specified the gauge groups and matter content of these four-dimensional worlds.

None of the models with only untwisted states contains a four-plane world in which the massless spectrum would match the world in which we live. Typically, one finds no chiral states in anomaly-free models, and/or the gauge groups do not resemble the standard model or any of the GUT group.

Among models where anomalies are canceled by some twisted states, the four-dimensional models are closely related to those obtained from compactifying $E_8 \times E_8$ heterotic string theory on T^6/\mathbb{Z}_7 orbifold [10]. In the limit $x_{11} \rightarrow 0$, the *M*-theory orbifold models should have the

same massless spectra as the corresponding string theory orbifolds. We do not, at this stage, know the details of this limit, foremost because *M*-theory—unlike string theory—does not have a well-understood 'fundamental' description. However, our considerations do provide the necessary twisted states to cancel the anomalies, which also introduces some chiral states in the massless spectrum. In our models, five-dimensional planes connect pairs of four-plane worlds, which are otherwise separated from each other. Since there are no anomalies on these five-planes, possible additional gauge symmetries in these planes cannot be determined in this way [6–8, 12]. In some of our models, some of the twisted states extend through these five-planes; the other twisted states need not extend in this way and may be localized to the respective four-plane worlds. This is an open problem and needs further insight.

Our calculations in finding the \mathbb{Z}_7 invariant subgroups of E_8 heavily rely on *Mathematica*TM programs, and the procedure can be applied for any other orbifold group in general. The programming aspects of the relevant *Mathematica*TM code will be discussed in a separate report. One might think that orbifolding with higher order groups, such as \mathbb{Z}_8 or \mathbb{Z}_{12} would give us more realistic and smaller groups. This much is indeed true, but the number of twisted states in that case grows too fast for realistic application [10]; these orbifolds do not appear to be viable as potential candidates to relate *M*-theory with the real world. However, this is just an assumption, a complete calculation is necessary to arrive at such statement. Initially we started our research with \mathbb{Z}_N orbifold in mind and we have partially worked on \mathbb{Z}_8 and \mathbb{Z}_{12} . Getting the untwisted states for any of these orbifolds was easy, but for the twisted states we had to rely on string theory. Even though we have a general procedure (in principle) to find out the twisted states, practically the calculation needs some computational tools. As presently implemented, our *Mathematica*TM code for finding the twisted states has a significant limitation: it works for any string theory models with up to two U(1) factors. The obvious need for generalizations in this direction provides goals for further research.

We have used Wilson lines to break the four-dimensional gauge group to a more realistic standard-like model. The example we have presented gives the gauge groups on one of the upper or lower four-plane worlds. For a complete list of models, we need to find the symmetry breaking on the opposite four-plane world, take the $x_{11} \rightarrow 0$ limit, calculate the anomalies, and ensure their cancellation. Although this leads to a plethora of models, the symmetry groups on the four-planes are much smaller than those obtained without employing Wilson lines.

Finally, there are mechanisms in string theory to break the gauge symmetry in a way that reduces the rank of the gauge group [25–27]. The precise analog of this mechanism lacks in the *M*-theory context. From the above indications however, one would expect an *M*-theory mechanism to exist, such that its $x_{11} \rightarrow 0$ limit (with the more detailed dynamics taken into account), is that of [25–27]. This remains an open question.

Acknowledgments

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Appendix A. Subgroups of E_8

We find out all the subgroups of E_8 using the Dynkin diagram [28]. The procedure is to remove circles in all possible ways from the extended Dynkin diagram and read off the subgroup from the remaining circles. In this way, we get a total of 99 subgroups of E_8 given in table A1.

Table A1. All the subgroups of E_8 and the values of the identifiers. The entries under the headings k, m and r are defined in equations (3.2) and (3.5), respectively. Only the subgroups labeled by a check-mark in the 'o' column may occur in our \mathbb{Z}_7 -orbifold models.

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15 SO_{12} 30 0 6 \checkmark 65 SU_3^4 12 0 8 16 $SU_8 \times SU_2$ 29 1 8 66 $SU_5 \times SU_2$ 11 1 5 17 SU_8 28 0 7 \checkmark 67 $SU_4 \times SU_3 \times SU_2^2$ 11 2 7 18 $SO_{10} \times SU_4$ 26 0 8 68 $SU_4 \times SU_2^5$ 11 5 8 19 $SO_{10} \times SU_3 \times SU_2$ 24 1 8 69 $SU_3^3 \times SU_2^2$ 11 2 8 20 $SU_5 \times SU_5$ 24 0 8 70 SU_5 10 0 4
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$21 SO_{10} \times SU_3 \qquad \qquad 23 0 7 \checkmark 71 SU_4 \times SU_3 \times SU_2 10 1 6$
22 $SO_{10} \times SU_2^3$ 23 3 8 \checkmark 72 $SU_4 \times SU_2^4$ 10 4 7
23 $SU_7 \times SU_2^2$ 23 2 8 \checkmark 73 $SU_3^3 \times SU_2$ 10 1 7
24 $SO_{10} \times SU_2^2$ 22 2 7 \checkmark 74 $SU_3^2 \times SU_2^4$ 10 4 8
$25 SO_8 \times SU_5 \qquad 22 0 8 \checkmark 75 SU_4 \times SU_3 \qquad 9 0 5$
$26 SU_7 \times SU_2 \qquad 22 1 7 \checkmark 76 SU_4 \times SU_2^3 \qquad 9 3 6$
$27 SO_{10} \times SU_2 \qquad 21 1 6 \checkmark 77 SU_3^3 \qquad 9 0 6$
28 SU_7 21 0 6 \checkmark 78 $SU_3^2 \times SU_2^3$ 9 3 7
$29 SU_6 \times SU_4 \qquad 21 0 8 \checkmark 79 SU_3 \times SU_2^6 \qquad 9 6 8$
$30 SO_{10} \qquad \qquad 20 0 5 \qquad 80 SU_4 \times SU_2^2 \qquad 8 2 5$
$31 SU_5^2 \qquad \qquad 20 0 8 \qquad 81 SU_3^2 \times SU_2^2 \qquad 8 2 6$
$32 SO_8 \times SU_4 \times SU_2 19 1 8 82 SU_3 \times SU_2^5 8 5 7$
33 $SU_6 \times SU_3 \times SU_2$ 19 1 8 83 SU_2^8 8 8 8
$34 SO_8 \times SU_4$ 18 0 7 84 $SU_4 \times SU_2$ 7 1 4
35 $SO_8 \times SU_3^2$ 18 0 8 85 $SU_3^2 \times SU_2$ 7 1 5
36 $SU_6 \times SU_3$ 18 0 7 86 $SU_3 \times SU_2^4$ 7 4 6
37 $SU_6 \times SU_2^3$ 18 3 8 87 SU_2^7 7 7 7
$38 SO_8 \times SU_3 \times SU_2^2 17 2 8 88 SU_4 6 0 3$
$39 SU_6 \times SU_2^2 \qquad 17 2 7 \qquad 89 SU_3^2 \qquad 6 0 4$
40 $SU_5 \times SU_4 \times SU_2$ 17 1 8 90 $SU_3 \times SU_2^3$ 6 3 5
41 $SO_8 \times SU_3 \times SU_2$ 16 1 7 \checkmark 91 SU_2^6 6 6 6
42 $SO_8 \times SU_2^4$ 16 4 8 \checkmark 92 $SU_3^2 \times SU_2^2$ 5 2 4
43 $SU_6 \times SU_2$ 16 1 6 \checkmark 93 SU_2^5 5 5 5

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	Table A1. (C										
	Subgroups	k	т	r	0		Subgroups	k	т	r	0
44	$SU_5 imes SU_4$	16	0	7	\checkmark	94	$SU_3 \times SU_2$	4	1	3	
45	$SU_5 imes SU_3^2$	16	0	8	\checkmark	95	SU_2^4	4	4	4	
46	$SO_8 \times SU_3$	15	0	6	\checkmark	96	SU_3	3	0	2	
47	$SO_8 imes SU_2^3$	15	3	7	\checkmark	97	SU_2^3	3	3	3	
48	SU_6	15	0	5	\checkmark	98	SU_2^2	2	2	2	
49	$SU_5 imes SU_3 imes SU_2^2$	15	2	8	\checkmark	99	SU_2	1	1	1	
50	$SU_4^2 \times SU_3$	15	0	8	\checkmark	100	U_1^8	0	0	8	

Appendix B. \mathbb{Z}_7 -invariant subgroups of E_8 and generalizations

Among the subgroups of E_8 , we are only interested in those that are marked with a check in column 'o' of table A1. These are the possible candidates as \mathbb{Z}_7 invariant subgroups. We arrive at this conclusion by finding all the values of k_V (3.3), each of which is the number of E_8 roots that satisfy the condition $P^I \cdot V^I \in \mathbb{Z}$ for a given shift vector V^I , with V^I ranging over all \mathbb{Z}_7 shift vectors. This narrows down our choices to 30 subgroups of E_8 .

Next, we calculate the values of m (the number of SU_2 factors in a group) for all of these choices, manually from table A1. If k and m do not specify the group we find the values of r (rank of a group), also manually, from the table.

Finally, we use *Mathematica*TM to calculate the values of the identifiers k, m and r from the surviving roots of E_8 and compare them with the values in table A1 to determine the \mathbb{Z}_7 invariant subgroups of E_8 . This reduces our choices to 14 subgroups only (see table B1).

Table B1. Subgroups of E_8 invariant under \mathbb{Z}_7 shifts.

	Subgroup		Subgroup		Subgroup		Subgroup
1	E_7	5	<i>SO</i> ₁₂	9	SU_8	13	$SU_5 imes SU_4$
2	$E_6 \times SU_2$	6	$SO_{10} \times SU_3$	10	$SU_7 \times SU_2$	14	$SU_5 \times SU_3 \times SU_2$
3	E_6	7	$SO_{10} \times SU_2$	11	SU_7		
4	SO_{14}	8	$SO_8 \times SU_3$	12	$SU_6 \times SU_2$		

A closing remark. When considering higher-order orbifolds, the above identifiers, k, m, r will not identify the subgroups uniquely. However, the counting of the SU(2) factors can be generalized in a very simple way as follows. The SU(n) groups are uniquely characterized by the fact that they have $\binom{n}{2}$ positive roots that form a Pascal triangle:

$$E_{\alpha^{1}+\alpha^{2}+\dots+\alpha^{n-1}}$$

$$\cdots$$

$$\cdots$$

$$\cdots$$

$$E_{\alpha^{1}+\alpha^{2}} E_{\alpha^{2}+\alpha^{3}} \cdots E_{\alpha^{n-2}+\alpha^{n-1}}$$

$$E_{\alpha^{1}} E_{\alpha^{2}} E_{\alpha^{3}} \cdots E_{\alpha^{n-2}} E_{\alpha^{n-1}},$$
(B.1)

where $E_{\alpha^i + \alpha^j} = [E_{\alpha^i}, E_{\alpha^j}]$, etc. This implies an analogous system of relations for the vectors z^i , to be found among the relations such as equations(3). One then first identifies all the SU(2) sub-systems in this way, and then all other SU(n) factors, increasing *n* incrementally, one by one, from n = 3 and until the subgroup of E_8 has been identified. The corresponding number

of SU(n) factors may then be labeled m_n , where m_2 is the *m* as defined in equations (3.5) and (3.8).

The special treatment of the SU(n) subgroups was simply for illustration purposes; other Lie groups also have characteristic positive root systems, encoding the correspondingly characteristic commutation relations among the positive roots. The SU(2) subgroup factors remain, of course, the simplest to find.

In general then, for any system of Γ -invariant roots z^i , we find the complete system of ternary relations such as equations (3). Within this system, we identify a sub-system of relations as corresponding to the characteristic commutation relations of a Lie group *H*. This identifies *H* as a factor in the maximal Γ -invariant subgroup of E_8 .

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